

11. Missing values

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Missing data

- Missing data is common in longitudinal studies. Data is **missing** if a measurement that was **intended** to be taken is not taken, or not available for another reason.
- The **reason** for missing measurements is important. For example:
 - The lab technician accidentally destroyed the blood sample.
 - Measurements below the limit of detection are set to missing (censoring).
 - The values are missing because the subjects did not show up for their scheduled visits.

Notation

Assumption: It is planned to take $n_i = n$ measurements per subject.

- Vector of responses (observed and missing) for subject i :

$$\mathbf{Y}_i = (Y_{i1}, \dots, Y_{in})^T$$

- $R_{ij} = 1$, if Y_{ij} is observed, otherwise $R_{ij} = 0$. For each subject a vector

$$\mathbf{R}_i = (R_{i1}, \dots, R_{in})^T$$

is obtained.

- \mathbf{R}_i results in a division of \mathbf{Y}_i into two components \mathbf{Y}_i^o (observed) and \mathbf{Y}_i^m (missing).
- Subjects with $R_{ij} = 1$ for all j (i.e. without missing values) are called **completers**.

Missing data patterns

- **Dropout** / loss-to-follow-up / attrition:

Whenever Y_{ij} is missing, so are all Y_{ik} for $k \geq j$.

Pattern: $\mathbf{R}_i = (R_{i1}, \dots, R_{i(D_i-1)}, R_{iD_i}, \dots, R_{in})^T = (1, \dots, 1, 0, \dots, 0)^T$
with dropout indicator

$$D_i = 1 + \sum_{j=1}^n R_{ij}.$$

- **Intermittent** missing values

Example patterns: $\mathbf{R}_i = (1, 1, 0, 1, \dots, 1)^T$, $\mathbf{R}_i = (1, 0, 1, 0, 1, \dots)^T$.

Questions

For missing values, is it allowed to:

- calculate means and variances?
- use ML based methods?
- use the GEE method?

Important: The answer for each method depends on the missing mechanism

- missing completely at random (MCAR)
- missing at random (MAR)
- not missing at random (NMAR)

(Rubin, 1976)

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Missing completely at random (MCAR)

$$P(R_{ij} = 1 | \mathbf{Y}_i^o, \mathbf{Y}_i^m, \mathbf{X}_i) = P(R_{ij} = 1 | \mathbf{X}_i).$$

for $i = 1, \dots, N$, $j = 1, \dots, n$.

- The probability of missingness ($P(R_{ij} = 0)$) is not related to any of the responses. The distribution of the Y_{ij} is the same as that of the Y_{ij}^o , given \mathbf{X}_i .
- Other (stronger) definition: also no connection between the covariates and the occurrence of missing values,

$$P(R_{ij} = 1 | \mathbf{Y}_i^o, \mathbf{Y}_i^m, \mathbf{X}_i) = P(R_{ij} = 1).$$

The observed data are a random sample of the complete data.

Examples MCAR

- The lab technician accidentally destroyed the blood sample.
- Overlooked question on questionnaire
- Questionnaire lost in the mail
- Did not come to examination because of a death in the family
- Rotating panel: patients by design rotate out of the study after providing a pre-determined number of measurements.
- Death due to a car accident
- Moving, but with exceptions

→ Try to find out from data collector

Examples MCAR

Example for

$$P(R_{ij} = 1 | \mathbf{Y}_i^o, \mathbf{Y}_i^m, \mathbf{X}_i) = P(R_{ij} = 1 | \mathbf{X}_i).$$

Weight and sex. Regardless of the weight itself women hesitate to give their weight:

$$P(R_{ij} = 1 | \mathbf{Y}_i^o, \mathbf{Y}_i^m, \mathbf{X}_i) = P(R_{ij} = 1 | G_i)$$

with

$$P(R_{ij} = 1 | G_i = W) > P(R_{ij} | G_i = M).$$

This kind of MCAR is called MAR if the stronger definition of MCAR is used.

Missing at random (MAR)

$$P(R_{ij} = 1 | \mathbf{Y}_i^o, \mathbf{Y}_i^m, \mathbf{X}_i) = P(R_{ij} = 1 | \mathbf{Y}_i^o, \mathbf{X}_i).$$

for $i = 1, \dots, N$, $j = 1, \dots, n$.

- The probability of missingness ($P(R_{ij} = 0)$) is not related to the value that would have been observed if the value had not been missing, but depends on the observed values.
- The distribution of \mathbf{Y}_i^m conditional on \mathbf{Y}_i^o (and \mathbf{X}_i) is the same as the corresponding distribution among the complete cases.
- In practice, MAR is more frequent than MCAR!

Examples MAR

- Ethical considerations require that a patient is removed from the study if Y_{ij} falls outside a certain range of values (patient is not responding to the treatment).
 - Creatinine level is too bad \rightarrow patient is dialyzed in a different department/hospital.
 - Respiratory problems in children \rightarrow family moves to a place with better air quality.
- . . . always assuming the decision is associated only with observed values Y_{ij}^o .

Not missing at random (NMAR)

$$P(R_{ij} = 1 | \mathbf{Y}_i^o, \mathbf{Y}_i^m, \mathbf{X}_i)$$

cannot be simplified as with MCAR or MAR, $i = 1, \dots, N$, $j = 1, \dots, n$.

- The probability of missingness ($P(R_{ij} = 0)$) depends on the observed as well as on the unobserved values.
- Also called [informative missingness](#).
- NMAR is (unfortunately!) quite common.

Examples NMAR

- In a study on pain relief, patients with severe pain are less likely to answer the phone and give their current pain status.
- Heavy people hesitate to give their weight.
- Major respiratory problems → hospital!

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Dropout

- For **intermittent missing values**, the reason is often known, as subjects remain in the study → find out whether MCAR or MAR assumption is tenable → analysis of available data
- For **dropout**, we often have to suspect a relation between the dropout and the measurement process (MAR or NMAR).

Dropout: Possible reasons

- Other disease, death \rightarrow MCAR only if unrelated to what is studied!
- Uncooperative patient \rightarrow MCAR if unrelated to what is studied
- Ineffective therapy \rightarrow MAR if decision based on Y_{ij}^o , otherwise NMAR
- Moving \rightarrow MCAR, MAR or NMAR depending on reason
- Patient feeling too sick, which would be reflected in $\mathbf{Y}_i^m \rightarrow$ NMAR
- Unknown (“lost to follow-up”: LOFU) \rightarrow ??

Dropout: Graphical display

Examples:

- “Survival Curve”
- Individual curves grouped by dropout time

For MCAR, the history of y_{ij} values of people “about to drop out” should be the same (or conditional on \mathbf{X}_i) as that of those not dropping out.

→ compare visually or for formal test see [Diggle \(1989\)](#).

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Likelihood-based inference and missing data

For likelihood-based inference, it is most important to distinguish between MCAR/MAR on the one hand, and NMAR on the other hand.

The joint density of $(\mathbf{Y}^o, \mathbf{Y}^m, \mathbf{R})$ is

$$f(\mathbf{y}^o, \mathbf{y}^m, \mathbf{r} | \mathbf{X}_i) = f(\mathbf{y}^o, \mathbf{y}^m | \mathbf{X}_i) f(\mathbf{r} | \mathbf{y}^o, \mathbf{y}^m, \mathbf{X}_i).$$

The joint density of the observable data then factors as

$$\begin{aligned} f(\mathbf{y}^o, \mathbf{r} | \mathbf{X}_i) &= \int f(\mathbf{y}^o, \mathbf{y}^m | \mathbf{X}_i) f(\mathbf{r} | \mathbf{y}^o, \mathbf{y}^m, \mathbf{X}_i) d\mathbf{y}^m \\ &\stackrel{MCAR/MAR}{=} \int f(\mathbf{y}^o, \mathbf{y}^m | \mathbf{X}_i) d\mathbf{y}^m f(\mathbf{r} | \mathbf{y}^o, \mathbf{X}_i) \\ &= f(\mathbf{y}^o | \mathbf{X}_i) f(\mathbf{r} | \mathbf{y}^o, \mathbf{X}_i). \end{aligned}$$

Likelihood-based inference and missing data

The log-likelihood then is

$$\log L = \log f(\mathbf{y}^o | \mathbf{X}_i) + \log f(\mathbf{r} | \mathbf{y}^o, \mathbf{X}_i).$$

It is maximized by maximizing the two terms separately. Since the second term contains no information about the distribution of \mathbf{Y}^o , we can ignore it for inference about \mathbf{Y}^o .

Thus, MCAR/MAR are sometimes jointly referred to as **ignorable missingness**.

Likelihood-based inference and missing data

However,

- “ignorability” depends on the likelihood being the basis for inference (and being correctly specified!). (Standard) GEE is only valid under the stronger assumption of MCAR.
- if $\log f(\mathbf{y}^o)$ and $\log f(\mathbf{r}|\mathbf{y}^o)$ share parameters, ignoring $\log f(\mathbf{r}|\mathbf{y}^o)$ will result in a loss of efficiency.
- this assumes that the distribution of \mathbf{Y}^o is the target of inference.

Example: A clinical trial for treatment of a life-threatening disease. Dropout is due to patients’ death. Inference about the distribution of the survival time and the conditional distribution of \mathbf{Y}^o given survival may be more meaningful than about the unconditional distribution of \mathbf{Y}^o .

GEE and missing data

- GEE is used for its consistency under misspecified covariance structures and without distributional assumptions if the mean model is correct.

- Score equation:

$$\sum_{i=1}^N \frac{\partial \boldsymbol{\mu}_i}{\partial \boldsymbol{\beta}} \mathbf{V}_i^{-1} (\mathbf{y}_i - \boldsymbol{\mu}_i) = \mathbf{0}$$

- Only consistent for **MCAR!**
- Consider the probability p_{ij} of observing Y_{ij} conditional on the history $y_{i1}, \dots, y_{i,j-1}$ and covariates.
- **Assumption:** Measurement y_{ij} is representative of missing values from subjects with similar history.

A variation of GEE

- Robins et al (1995) propose a weighted GEE for MAR, where each observed measurement gets the weight $1/p_{ij}$ (inverse probability weighting), upweighting measurements with small probabilities ($\mathbf{P}_i = \text{diag}(p_{ij})$):

$$\sum_{i=1}^N \frac{\partial \boldsymbol{\mu}_i}{\partial \boldsymbol{\beta}} \mathbf{V}_i^{-1} \mathbf{P}_i^{-1} (\mathbf{y}_i - \boldsymbol{\mu}_i) = \mathbf{0}.$$

- The resulting estimator is consistent under certain conditions including that the p_{ij} are consistently estimated. → More suitable for large samples!
- It requires a parametric model for the p_{ij} (with the data providing sparse information on the dropout process), in a setting where a parametric model for the covariance structure is avoided.

Example 1 (Little, 2008)

Suppose $n_i = 2$ for all i , and we have the normal model

$$\begin{pmatrix} Y_{i1} \\ Y_{i2} \end{pmatrix} \stackrel{iid}{\sim} \mathcal{N} \left(\begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}, \begin{pmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{12} & \sigma_{22} \end{pmatrix} \right) = \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma}).$$

Suppose that Y_{i1} is observed for all N subjects, but Y_{i2} only for the first r (dropout). MAR assumption: missingness of Y_{i2} can depend on Y_{i1} , but conditional on Y_{i1} , it does not depend on Y_{i2} . The likelihood is

$$\begin{aligned} L_{ign}(\boldsymbol{\mu}, \boldsymbol{\Sigma} | \mathbf{Y}^o) &= \prod_{i=1}^r |\boldsymbol{\Sigma}|^{-1/2} \exp\left(-\frac{1}{2}(\mathbf{Y}_i - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{Y}_i - \boldsymbol{\mu})\right) \quad (11.1) \\ &\quad \times \prod_{i=r+1}^N \sigma_{11}^{-1/2} \exp\left(-\frac{1}{2}(Y_{i1} - \mu_1)^2 / \sigma_{11}\right). \end{aligned}$$

Example 1

The likelihood can be factored into the marginal distribution of Y_{i1} and the conditional distribution of Y_{i2} given Y_{i1} . The ML estimates then are

$$\begin{aligned}\hat{\mu}_1 &= \frac{1}{N} \sum_{i=1}^N y_{i1} & \hat{\sigma}_{11} &= \frac{1}{N} \sum_{i=1}^N (y_{i1} - \hat{\mu}_1)^2 \\ \hat{\mu}_2 &= \bar{y}_2 + \hat{\beta}_{2|1}(\hat{\mu}_1 - \bar{y}_1) & \hat{\sigma}_{22} &= s_{22} + \hat{\beta}_{2|1}^2(\hat{\sigma}_{11} - s_{11}) \\ & & \hat{\sigma}_{12} &= \hat{\beta}_{2|1}\hat{\sigma}_{11}\end{aligned}$$

where \bar{y}_j and s_{jk} are sample means and (co)variances from the complete cases and $\hat{\beta}_{2|1} = s_{12}/s_{11}$ is the regression coefficient regressing Y_{i2} on Y_{i1} for the complete cases.

Example 1

- Large-sample standard errors can be based on the observed information matrix, or obtained based on bootstrapping the observed data.
- The ML estimate $\hat{\mu}_2$ adjusts \bar{y}_2 using available information on the difference $(\hat{\mu}_1 - \bar{y}_1)$ between averages based on all cases and on complete cases only, and information on the association between Y_{i1} and Y_{i2} .
- By contrast, calculating the empirical means and variances for the two time points would result in unadjusted estimates \bar{y}_2 and s_{22} . So would using GEE with a working independence assumption corresponding to ML estimation with $\sigma_{12} = 0$.

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Overview of data analysis methods for missing values

- Complete case analysis
- Available data analysis
- Imputation
- Selection models

Complete case analysis

- Non-completers are completely deleted.
- Inefficient, wasteful of data (in extreme cases, there are no subjects without missing values).
- Only valid for MCAR (rare in practice). For MAR or NMAR, this can introduce bias.
- Useful only if you are only interested in the completers, otherwise not recommended.

Available data analysis

- General term for methods that can analyse the available data with unequal n_i .
- More efficient than complete case analysis.
- Only valid for MCAR (rare in practice) or for MAR if likelihood-based methods are used.

Example 1 continued

$$(Y_{i1}, Y_{i2})^T \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$$

with Y_{i2} observed only for the first r subjects.

- A complete case analysis would be biased for MAR, yielding $\hat{\mu}_j = \bar{y}_j$, $j = 1, 2$, based only on completers.
- An available case analysis for MAR is fine if ML with general $\boldsymbol{\Sigma}$ is used, but would be biased for independent mean estimation or GEE with incorrect working covariance (cf. p. 20-22).

Imputation methods

- **Last value carried forward**: if y_{ij} is the last observed value, y_{ik} is set to y_{ij} for subsequent missing values. Variations:
 - Estimate a time-trend and extrapolate.
 - Baseline value carried forward, worst value carried forward.

Strong and often unrealistic assumptions! Data with less variability, over-optimistic standard errors. Not recommended.

- Methods which draw imputed \mathbf{y}_i^m from $f(\mathbf{y}_i^m | \mathbf{y}_i^o, \mathbf{X}_i)$:
 - **Propensity based methods**
 - **Predictive mean matching**

Subsequent analyses are valid under MAR or MCAR. **Multiple imputation** also ensures that uncertainty is properly accounted for.

Propensity based imputation

- These methods are based on a model for the dropout probability, such as e.g.

$$\log \left[\frac{P(D_i = k | D_i \geq k, Y_{i1}, \dots, Y_{ik})}{P(D_i > k | D_i \geq k, Y_{i1}, \dots, Y_{ik})} \right] = \theta_1 + \theta_2 Y_{ik-1}$$

Which missing mechanism do we have here?

- Missing responses are imputed based on responses of subjects with similar estimated dropout probability but who did not drop out.

Predictive mean matching

- Regression models for Y_{ik} based on Y_{i1}, \dots, Y_{ik-1} :

$$E(Y_{ik}) = \gamma_1 + \gamma_2 Y_{i1} + \dots + \gamma_k Y_{ik-1}$$

- Each model is estimated based on the subjects with $D_i > k$.
- This results in estimates $\hat{\gamma}$ and $\hat{\sigma}$ (error variance).
- To account for estimation uncertainty, values γ^* and σ^* are drawn from the distribution of $\hat{\gamma}$ (and $\hat{\sigma}$).
- This gives the imputed value

$$\gamma_1^* + \gamma_2^* Y_{i1} + \dots + \gamma_k^* Y_{ik-1} + \sigma^* e_i,$$

with simulated $e_i \sim \mathcal{N}(0, 1)$. (Can be generalized to GLMs.)

Multiple imputation

- Each missing value is imputed by several (typically $5 \leq m \leq 10$) values. Why is this useful?
- \rightarrow m data sets are generated
 \rightarrow m estimates $\widehat{\beta}^{(k)}$ und $\widehat{\text{Cov}}(\widehat{\beta}^{(k)})$
- The result is (Rubin, 1987)

$$\bar{\beta} = \frac{1}{m} \sum_{k=1}^m \widehat{\beta}^{(k)}$$

$$\widehat{\text{Cov}}(\bar{\beta}) = \frac{1}{m} \sum_{k=1}^m \widehat{\text{Cov}}(\widehat{\beta}^{(k)}) + \left(1 + \frac{1}{m}\right) \frac{1}{m-1} \sum_{k=1}^m \left(\widehat{\beta}^{(k)} - \bar{\beta}\right) \left(\widehat{\beta}^{(k)} - \bar{\beta}\right)^T.$$

Further alternatives

- Weighting methods for MAR (cf. slide 23 for GEE), see e.g. [Fitzmaurice et al. \(2004\)](#), Chapter 14.
- The EM-algorithm for MAR, see e.g. [Molenberghs & Verbeke \(2005\)](#), Chapter 28.

The EM-algorithm is also an alternative if values are missing below the limit of detection / above a cut-off value (censoring).

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Models for dropout

- **Idea:** Joint modeling of the dropout mechanism and \mathbf{Y}_i
- Two important approaches: [selection models](#) and [pattern mixture models](#)
- Selection models are based on the factorization

$$f(\mathbf{y}_i, \mathbf{r}_i | \mathbf{X}_i, \boldsymbol{\theta}, \boldsymbol{\psi}) = f(\mathbf{y}_i | \mathbf{X}_i, \boldsymbol{\theta}) f(\mathbf{r}_i | \mathbf{y}_i, \mathbf{X}_i, \boldsymbol{\psi})$$

with $f(\mathbf{r}_i | \mathbf{y}_i, \mathbf{X}_i, \boldsymbol{\psi}) = f(\mathbf{r}_i | \mathbf{X}_i, \boldsymbol{\psi})$ for MCAR and $f(\mathbf{r}_i | \mathbf{y}_i, \mathbf{X}_i, \boldsymbol{\psi}) = f(\mathbf{r}_i | \mathbf{y}_i^o, \mathbf{X}_i, \boldsymbol{\psi})$ for MAR.

- Pattern mixture models are based on the factorization

$$f(\mathbf{y}_i, \mathbf{r}_i | \mathbf{X}_i, \boldsymbol{\nu}, \boldsymbol{\delta}) = f(\mathbf{r}_i | \mathbf{X}_i, \boldsymbol{\delta}) f(\mathbf{y}_i | \mathbf{r}_i, \mathbf{X}_i, \boldsymbol{\nu}).$$

Example 1 continued

Consider a selection model for NMAR dropout:

$$(Y_{i1}, Y_{i2})^T \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$$

$$(R_{i2} | Y_{i1}, Y_{i2}) \sim \text{Bernoulli}(\pi_i)$$

$$\text{logit}(\pi_i) = \psi_0 + \psi_1 Y_{i1} + \psi_2 Y_{i2}.$$

The likelihood is

$$\begin{aligned} L(\boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\psi} | \mathbf{R}, \mathbf{Y}^o) &= \prod_{i=1}^r |\boldsymbol{\Sigma}|^{-1/2} \exp\left(-\frac{1}{2}(\mathbf{Y}_i - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{Y}_i - \boldsymbol{\mu})\right) \pi_i(\boldsymbol{\psi}) \\ &\times \prod_{i=r+1}^N \int |\boldsymbol{\Sigma}|^{-1/2} \exp\left(-\frac{1}{2}(\mathbf{Y}_i - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{Y}_i - \boldsymbol{\mu})\right) (1 - \pi_i(\boldsymbol{\psi})) dY_{i2}. \end{aligned}$$

Example 1 continued

- Maximization requires an iterative algorithm such as the EM algorithm
- The model is weakly identified, and identification is strongly depending on the model assumptions.
- Thus, it is preferred to either make additional assumptions such as $\psi_1 = 0$ or $\psi_2 = 0$, or to conduct a sensitivity analysis for a range of plausible ψ .
- For $\psi_2 = 0$ (MAR), the likelihood reduces to

$$L(\boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\psi} | \mathbf{R}, \mathbf{Y}^o) = L_{ign}(\boldsymbol{\mu}, \boldsymbol{\Sigma} | \mathbf{Y}^o) \prod_{i=1}^r \pi_i(\boldsymbol{\psi}) \prod_{i=r+1}^N (1 - \pi_i(\boldsymbol{\psi})),$$

where $L_{ign}(\boldsymbol{\mu}, \boldsymbol{\Sigma} | \mathbf{Y}^o)$ is given by (11.1), and ML estimation of $\boldsymbol{\mu}$ and $\boldsymbol{\Sigma}$ can be based on the ignorable likelihood, as discussed in example 1.

Overview applicability of methods

	MCAR	MAR	NMAR
Expected value, variance	yes (or conditional on \mathbf{X}_i)	no	no
Available case analysis	yes	no/yes	no
Complete case analysis	yes, but inefficient	no	no
GEE	yes	no, or weighted GEE	no
ML methods	yes	yes	no
(Multiple) imputation from $f(\mathbf{y}_i^m \mathbf{y}_i^o, \mathbf{X}_i)$	yes	yes	no
Selection models	yes	yes	yes

Discussion

- ML (or Bayesian) inference for ignorable missingness is similar to corresponding complete data analyses. However, randomness (MAR) of missings is an assumption which cannot be verified from the observed data.
- Non-ignorable models are more challenging, have problems with lack of identifiability and require assumptions about the missing data mechanism, e.g. a parametric model for R_i given Y_i and X_i in selection models.
- Oftentimes, especially in potential NMAR cases, a sensitivity analysis under different assumptions is the most sensible alternative to make the dependence of results on assumptions transparent.

- If covariate values are also missing, additional work is required, with multiple imputation being one option.
- Read more e.g. in [Diggle et al \(2002\)](#), [Molenberghs & Verbeke \(2005\)](#) or [Fitzmaurice et al. \(2008\)](#).